Online Machine Learning

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- Online machine learning (OML) is a method of machine learning in which:
 - data becomes available in a sequential order
 - is used to update our best predictor for future data at each step, as opposed to batch learning techniques which generate the best predictor by learning on the entire training data set at once

Difference to standard approach



- Online prediction refers to the problem of prediction in the online protocol (sequential prediction problems):
 - Nature outputs some side information
 - Predictor outputs a prediction
 - Nature outputs an observation
 - The cycle is repeated
- Difference to usual supervised learning:
 - Test and Train datasets are the same but the distinguish between train and test is through time

Motivation example

- A problem:
 - What is papaya?
 - How to find good papaya?

Motivation example

- A problem:
 - What is papaya?
 - How to find good papaya?
 - Buy papaya and let's try to predict if it is ok.



Motivation



- It is computationally infeasible to train over the entire dataset
 - So should train by mini-batches (or one-by-one)
- It is used in situations where it is necessary for the algorithm to dynamically adapt to new patterns in the data
 - Data changes too fast decrease lag
 - Fast tuning to important data trends

How to solve it?

- Recursive adaptive algorithms (Robbins and Monro - 1951)
- Stochastic approximation (Kushner and Clark, 1978)
- Adaptive filtering (Haykin 2002, 2010)

Model types



- Statistical models
 - Data samples are usually assumed to be i.i.d.
 - Algorithm just has a limited access to the data
- Adversarial models
 - They are looking at the learning problem as a game between two players (the learner vs the data generator)
 - The goal is to minimize losses regardless of the move played by the other player

I. Statistical online models



- Gradient descent
- Kalman filtering
- Kernel model
- SVM
- Folding-in

1. Batch gradient descent



$$W_{t+1} = W_{t} - \gamma_{t} \nabla_{w} \hat{J}_{L}(w_{t}) = W_{t} - \gamma_{t} \frac{1}{L} \sum_{i=1}^{L} \nabla_{w} Q(x_{i}, w_{t})$$

- When the learning rate γ are small enough, the algorithm converges towards a local minimum of the empirical risk $\hat{J}_{L}(w)$
- We can speed up convergence by replacing by positive matrix
- We should save all points from training dataset
- Compute average gradient for all points

Online gradient descent

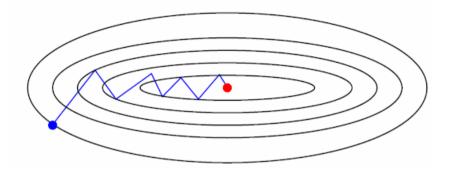


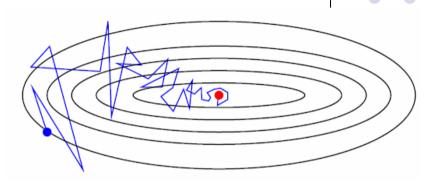
We don't do averaging

$$W_{t+1} = W_t - \gamma_t \nabla_w Q(x_t, W_t)$$

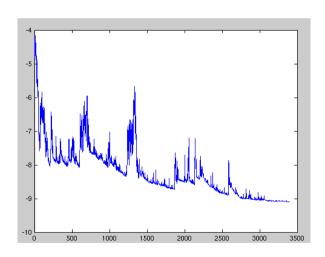
- Use just one point one at a time
- We hope that random selection will not perturbate the average behavior of the algorithm

Online gradient descent





- So we see weird behavior
- Is there a convergence?

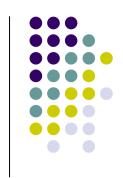


Online gradient descent



- The main question: is there a convergence?
- Theory: Yes!
 - When the learning rate decreases with an appropriate rate
 - We will get global minimum if objective function is convex, otherwise almost surely will get local minimum

Gradient descent optimizations



- There is a couple of GD optimizations:
 - Momentum (Sutton, R. S. 1986)
 - Nesterov accelerated gradient (Nesterov, Y. 1983)
 - AdaGrad (Duchi, J., Hazan, E., & Singer, Y. 2011)
 - Adadelta (extension of AdaGrad)
 - Stochastic average gradient (Le Roux, Schmidt, and Bach, 2012)

AdaGrad



- SGD with per-parameter learning rate
 - Large for more sparse parameters

$$g_t = \nabla_{w} Q(x_t, w_t)$$

$$G_{t,jj} = \sum_{k=1}^{t} g_{k,j}^{2}$$

$$w_{t+1} = w_t - \gamma \cdot diag \left(G_t + e\right)^{-1/2} \circ g_j$$

- Useful for sparse applications (for example NLP and image recognition)
 - Used in Google
 - Used for Glove model

2. Kalman filtering

- Recursive least squares filter
- Quasi-Newton algorithm

$$K_{t} = H_{t-1}^{-1}$$

$$K_{t+1} = K_{t} - \frac{(K_{t}x_{t})(K_{t}x_{t})^{T}}{1 + x_{t}^{T}K_{t}x_{t}}$$

$$W_{t+1} = W_{t} - K_{t+1}(y_{t} - W_{t}^{T}x_{t})^{T}x_{t}$$





• Batch regime:

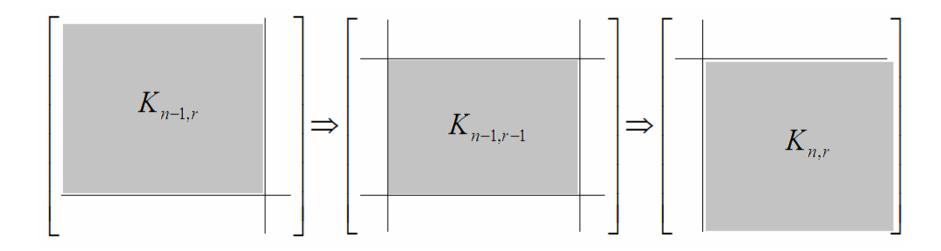
$$\alpha = K(\lambda)^{-1} Y = (K + \lambda I)^{-1} Y$$

$$K_{i,j} = \kappa(x_i, x_j), \quad i, j = 1, r$$



- The main problem: how to update inverse matrix
- It is possible to do in 2 stages:

$$K_{n-1, r}^{-1}(\lambda) \to K_{n-1, r-1}^{-1}(\lambda) \to K_{n, r}^{-1}(\lambda)$$

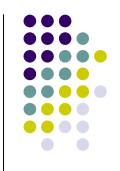


$$\alpha_n = \left(K_{n-1,r}(\lambda)\right)^{-1} \left(\lambda^{-1} \alpha_{n-1} + Y_{n-1,r}\right)$$

$$K_{n-1,r-1}^{-1} = \mathbf{R}_{r} K_{n-1,r}^{-1} \mathbf{R}_{r}^{\mathrm{T}} - (\mathbf{e}_{1}^{\mathrm{T}} K_{n-1,r}^{-1} \mathbf{e}_{1})^{-1} \mathbf{R}_{r} K_{n-1,r}^{-1} \mathbf{e}_{1} \mathbf{e}_{1}^{\mathrm{T}} K_{n-1,r}^{-1} \mathbf{R}_{r}^{\mathrm{T}}$$

$$K_{n,r}^{-1}(\lambda) = \begin{pmatrix} A & B \\ C & \delta_n^{-1} \end{pmatrix}$$

$$A = K_{n-1,r-1}^{-1} + \delta_n^{-1} \cdot K_{n-1,r-1}^{-1} \cdot k_{n-1,r-1}(x_n) \cdot k_{n-1,r-1}^{T}(x_n) \cdot K_{n-1,r-1}^{T}(x_n) \cdot K_{n-1,r-1}^{-1}(x_n) \cdot K_{n-1$$



$$B = -\delta_n^{-1} K_{n-1,r-1}^{-1} \cdot \mathbf{k}_{n-1,r-1} (x_n)$$

$$C = B^{\mathrm{T}} = -\delta_n^{-1} \mathbf{k}_{n-1,r-1}^{\mathrm{T}}(x_n) \cdot K_{n-1,r-1}^{-1}$$

$$\delta_{n} = \lambda^{-1} + k_{n,n} - k_{n-1,r-1}^{T}(x_{n}) \cdot K_{n-1,r-1}^{-1} \cdot k_{n-1,r-1}(x_{n})$$

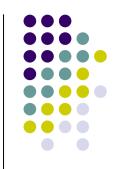
$$R_r = (0_r : I_{r-1})$$
 $e_1 = (1 \ 0 \ ... \ 0)^T$

$$\mathbf{k}_{n-1,r-1}^{\mathrm{T}}(x_n) = (\kappa(x_n, x_{n-r+1}) \dots \kappa(x_n, x_{n-1}))$$

$$\mathbf{k}_{n,n} = \kappa(x_n, x_n)$$



- The issue is a complexity
- Accumulate new observations in Gram matrix
- Control complexity of Gram matrix:
 - Sparsification
 - Prunning



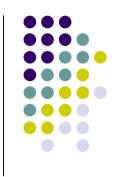
Approximate Linear Dependency (Engel 2004)

$$\delta_{t} = \min_{a} \left\| \sum_{j=1}^{m_{t-1}} a_{j} \phi(\tilde{x}_{j}) - \phi(x_{t}) \right\|^{2} \le v$$

$$\delta_{t} = \min_{a} \left\{ a^{T} \tilde{K}_{t-1} a - 2a^{T} \tilde{k}_{t-1}(x_{t}) + k_{tt} \right\}$$

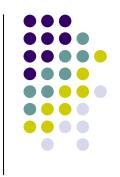
Novelty criterion (Haykin 2010)





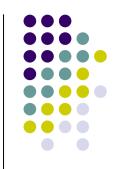
 More about kernels and recursive models: "Kernel Adaptive Filtering A Comprehensive Introduction (Adaptive and Learning Systems for Signal Processing, Communications and Control Series)" by Haykin





- The most famous is LASVM algorithms (Léon Bottou 2005-2011)
- There is a package for R:
 https://cran.r project.org/web/packages/lasvmR/index.html
- Uses 2 steps: PROCESS & REPROCESS
- In general add and delete support vectors

5. Folding-in



SVD decomposition for recommender systems

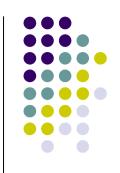
$$SVD(A) = U \times S \times V^{T}$$

$$A \approx U_{k} \times S_{k} \times V_{k}^{T}$$

$$P_{i,j} = \overline{r}_{i} + \left(U_{k} \sqrt{S_{k}}^{T}(i)\right) \cdot \left(\sqrt{S_{k}}^{T} V_{k}(j)\right)$$

- Challenge: building SVD is time consuming
- How to add new product, new customer?

Incremental Singular Value Decomposition



1) New product p (mx1)

$$\begin{bmatrix} A_k \\ \mathbf{m} \times (\mathbf{n+1}) \end{bmatrix} = \begin{bmatrix} U_k \\ \mathbf{m} \times \mathbf{k} \end{bmatrix} \begin{bmatrix} S_k \\ \mathbf{k} \times \mathbf{k} \end{bmatrix} \begin{bmatrix} V_k^T \\ \mathbf{k} \times (\mathbf{n+1}) \end{bmatrix} p' = p^T U_k S_k^{-1}$$

2) New customer c (1xn)

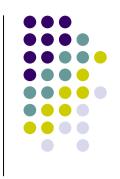
$$\begin{bmatrix} A_k \\ (m+1) \times n \end{bmatrix} = \begin{bmatrix} U_k \\ (m+1) \times k \end{bmatrix} \begin{bmatrix} S_k \\ k \times k \end{bmatrix} \begin{bmatrix} V_k^T \\ k \times n \end{bmatrix} \qquad C' = cV_k S_k^{-1}$$

II. Adversarial models



- Definition:
 - Player chooses w
 - Adversary chooses $l_t(w)$
 - Player suffers loss $l_t(w_t)$
 - Need to minimize cumulative loss
- Some standard algorithms:
 - Follow the leader (FTL)
 - Follow the regularised leader (FTRL)

Adversarial models



- We will not look at this models, but they have several advantages:
 - In contrast to statistical machine learning (stochastic), adversarial algorithms don't make stochastic assumptions about the data they observe, and even handle situations where the data is generated by a malicious adversary
 - So no i.i.d. assumption!

Pros and Cons of Online ML algorithms



- Online algorithms are
 - Often much faster
 - More memory-efficient
 - Can adapt to the best predictor changing over time
 - Hard to maintain in production
 - Hard to evaluate
 - Have problems with convergence

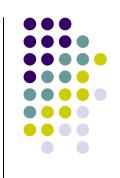




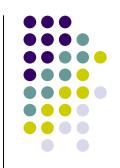
- Online Machine Learning can be used for:
 - Computer vision
 - Recommender systems
 - Predicting stock market trends
 - Deciding which ads to present on a web page
 - IoT applications

Put here your application...





- http://sebastianruder.com/optimizing-gradientdescent/index.html
- Kernel Adaptive Filtering A Comprehensive Introduction (Haykin 2010)
- The Kernel Recursive Least Squares Algorithm (Engel 2003)
- Foundations of Machine Learning (M. Mohri, A. Rostamizadeh, and A. Talwalkar 2012)



Thank you!

Questions?

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